### Large-aperture Metasurfaces for Broadband, Incoherent Optical Edge Detection Brandon Swartz<sup>1</sup>, Gregory Forcherio<sup>2</sup>, Jason Valentine<sup>1</sup> VANDERBILT <sup>1</sup>Mechanical Engineering, Vanderbilt University, Nashville, TN UNIVERSITY <sup>2</sup>Naval Surface Warfare Center, Crane, IN

# Motivation



# **Optical Edge Detection**

the computer vision system.<sup>1</sup>

We demonstrate edge detection as an example of optical feature detection.

Optical edge detection is achieved by engineering the point spread function (PSF) of an optical system.

**Coherent Illumination** 

**Feature Detector** 

light fields

Linear with respect to Linear with respect to light intensity

 $E_{out} = E_{in} * PSF$ 

 $I_{out} = I_{in} * PSF_{ic}$ 

 $PSF_{ic} = |PSF|^2$ 

**Coherent Point Spread Function** 

**Incoherent Point Spread Function** 

(Always positive)

Incoherent optical edge detection is less straightforward, because incoherent PSFs are always positive.<sup>4</sup>

To achieve a bipolar PSF for edge detection, the PSF must be decomposed into positive and negative components, which can be imaged separately and digitally subtracted.

The positive component of a Laplacian PSF can be formed with a refractive lens, while the negative component can be shaped by adding a specially designed metasurface.



Point spread functions for edge detection, such as the Laplacian PSF (above), always have positive and negative values.<sup>2</sup>

> Most previous demonstrations of optical edge detection have only worked for coherent illumination<sup>3</sup>; however, most real-world light sources are incoherent.

**Two PSF, Optoelectronic Solution for Incoherent Edge Detection** 

7<sup>2</sup> Kernel



convolution+ReLU max pooling fully nected+ReLU softmax

Feature detection is a computer vision systems designed to interpret information in images.

Digital computer vision systems typically require billions of floating-point operations per inference.

reducing the latency and power consumption of

### Metasurface Inverse Design

flat that use optics are subwavelength scatterers to modulate the phase, amplitude, and/or polarization of light waves.



We designed metasurfaces for edge detection in the long-wave infrared using non-resonant phase propagation meta-atoms, with spatially E. varying geometry.

The geometry of 17.6 million meta-atoms within a 23.7 mm aperture was simultaneously designed using an efficient, gradient-descent based inverse design algorithm.



#### **Design Features**

into a silicon substrate.

Broadband

The refractive lens in the optical system enables naturally broadband focusing. Using non-resonant meta-atoms, simulating broadband illumination during inverse design, and rewarding solutions with more gradual metasurface phase changes facilitated a design that works across the entire LWIR imaging band  $(7.5 - 13.5 \mu m)$ .

High Signal-to-Noise Ratio

Digital subtraction of similar images normally reduces net signal while magnifying noise. Our approach prioritizes signalto-noise ratio during inverse design, which results in solutions with maximum separation between positive and negative component PSFs, which minimizes unnecessary signal lost during digital subtraction.



atom geometries to decrease the error between a simulated and target edge image and maximum the simulated edge signal.

involved iteratively

updating the meta-





We demonstrated practical edge detection in real world conditions by imaging buildings around the Vanderbilt campus. The above edge image of the West End Tower shows a prominently highlighted outline of the tower.

For very small features below the limit for edge detection, our system acts as a highpass filter, increasing contrast by removing low-frequency background.





# References & Acknowledgements

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# Real World Imaging

# Single Aperture Design

We have also designed and fabricated a single aperture edge detector, capable of simultaneously capturing both positive and negative component images birefringent metasurfaces for polarization

> With a commercially available polarimetric camera, this could allow for optical edge detection in real time, without the need for complex alignment.

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